

# Conformal Prediction as Bayesian Quadrature

by Snell & Griffiths, ICML 2025 Outstanding Paper

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November 11, 2025

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- Bayesian Quadrature

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# Conformal Prediction 101

- Goal: Distribution-free uncertainty quantification in future observations of ANY black-box prediction models/algorithms
- How? Construct **prediction sets** that contain the ground-truth output with high probability  
i.e. finite-sample **coverage** guarantees in terms of coverage level  $1 - \alpha$
- How? Build a wrapper on top of black-box algos by converting prediction values into prediction sets.
- Setup: Assume having access to a **calibration set**  $(X_i, Y_i), i = 1, \dots, n$  the model hasn't seen, then given a new test point  $(X_{n+1}, Y_{n+1})$ , construct a prediction set  $\hat{C}_n$  such that

$$\mathbb{P} \left( Y_{n+1} \in \hat{C}_n(X_{n+1}) \right) \geq 1 - \alpha \Leftrightarrow \mathbb{P} \left( Y_{n+1} \notin \hat{C}_n(X_{n+1}) \right) \leq \alpha$$

# Key idea: use rank to form adjusted quantiles

- Denote **conformity score**  $s(x, y)$  as a (dis)agreement metric, e.g., absolute residual in regression, then the prediction set is formed by

$$\hat{\mathcal{C}}_n(X_{n+1}) = \{y : s(X_{n+1}, y) \leq \hat{q}_n\}$$

- $\hat{q}_n$  is the  $\frac{\lceil(1-\alpha)(n+1)\rceil}{n}$  quantile of  $s(X_1, Y_1), \dots, s(X_n, Y_n)$ , that is,  $\lceil(1-\alpha)(n+1)\rceil$  smallest of  $s(X_1, Y_1), \dots, s(X_n, Y_n)$
- Key assumption: **exchangeability** of scores  $s(X_i, Y_i), i = 1, \dots, n+1$
- Then, the rank of  $s_{n+1}$  is uniformly distributed over  $\{1, \dots, n+1\}$

Diagram illustrating the ranks of scores  $s(1), s(2), s(3), s(4), \dots, s_{\lceil(1-\alpha)(n+1)\rceil}, \dots, s_{(n+1)}$ . A bracket under the first  $\lceil(1-\alpha)(n+1)\rceil$  scores is labeled  $\geq 1 - \alpha$  fraction.

- $\implies \mathbb{P}(s(X_{n+1}, Y_{n+1}) \leq \hat{q}_n) \in \left[1 - \alpha, 1 - \alpha + \frac{1}{n+1}\right)$

# Regression Example

A Taste of Conformal Prediction by Emmanuel Candès starting at 10:12

# Split & Full Conformal Prediction

- Statistical & Computational tradeoff: how to exploit accessible data  $\{X_i, Y_i\}_{i=1}^n$  at hand?
- Split CP:
  - **split** data into training set  $D_1$  & calibration set  $D_2$   
 $D_1 \cup D_2 = \{1, \dots, n\}, D_1 \cap D_2 = \emptyset$
  - fit prediction model  $\hat{f}_{D_1}$  using  $D_1$ , compute scores using  $D_2$
  - train model once (**fast**), but lose statistical efficiency due to the sample splitting (only use half the data points to fit the model)
- Full CP:
  - use all data points for training and calibration via **leave-one-out** fitting
  - fit model  $\hat{f}_{-i}$  using all data except  $(X_i, Y_i)$ , and compute score  $s_i$  for each  $i = 1, \dots, n$
  - train model  $n$  times (**expensive**), but get exact coverage with tighter prediction sets
- Exchangeability needed for both! (Counterexamples: time series, covariate shift, heteroscedastic data  $\Rightarrow$  modified CP methods)

# Concrete Algorithm (Full CP, split as a special case)

- 1 Propose a test query value  $y$
- 2 Pick any conformity score  $s(x, y)$  (residual score  $s(x, y) = |y - \hat{\mu}(x)|$ )
- 3 Fit model to all  $n + 1$  data via a symmetric algorithm to  $(X_1, Y_1), (X_2, Y_2), \dots, (X_{n+1}, y) \sim S(X_i, Y_i)$
- 4 Compute quantile  $\hat{q}_n \triangleq Q_{\frac{\lceil (1-\alpha)(n+1) \rceil}{n}}(S(X_i, Y_i))$   
note:  $Q_{1-\alpha} \{s_i : i \in \mathcal{I}_{\text{cal}}\}$  for split CP
- 5 If  $S(X_{n+1}, y) \leq \hat{q}_n$ , include  $y$  in prediction set  $\hat{\mathcal{C}}_n$

# Review of Statistical Decision Theory

Let  $z = (z_1, \dots, z_n)$  be a set of calibration data  $\{(x_i, y_i)\}_{i=1}^n$ . Denote  $\theta$  as the likelihood parameter and  $\lambda(z)$  as a control parameter chosen based on  $z$ . Loss  $L(\theta, \lambda(z))$  is incurred by selecting  $\lambda$  when the true nature is  $\theta$ .

- risk

$$R(\theta, \lambda) = \int L(\theta, \lambda(z)) f(z | \theta) dz$$

- maximum risk

$$\bar{R}(\lambda) = \sup_{\theta} R(\theta, \lambda)$$

- average risk

$$r(\pi, \lambda) = \int R(\theta, \lambda) \pi(\theta) d\theta$$

- posterior risk

$$r(\lambda | z) = E(L_{\lambda} | z) = \int L(\theta, \lambda(z)) \pi(\theta | z) d\theta$$

- Find  $\lambda$  to control  $\bar{r}(\lambda) \triangleq \sup_{\pi} r(\pi, \lambda) = \sup_{\theta} R(\theta, \lambda) = \bar{R}(\lambda) \leq \alpha$



# Conformal Risk Control (Angelopoulos et al, 2024)

- Generalize to per-sample loss functions  $\ell(z, \lambda) \equiv \ell(\mathcal{C}_\lambda(x), y)$  that are assumed to be **monotonic** of a single parameter  $\lambda$ . The risk is

$$R(\theta, \lambda) = \int \ell(z_{\text{new}}, \lambda) f(z_{\text{new}} | \theta) dz_{\text{new}} = \mathbb{E}_{f(z|\theta)} [\ell(\mathcal{C}_\lambda(X_{n+1}), Y_{n+1})]$$

- Goal: control expected loss (risk) under minimal assumptions (exchangeability), e.g., false positive rate, F1 score, conditional error

$$\begin{aligned} & \mathbb{E} [\ell(\mathcal{C}_{\lambda_{\text{crc}}}(X_{n+1}), Y_{n+1})] \leq \alpha \\ \lambda_{\text{crc}} & \triangleq \inf \left\{ \lambda : \frac{1}{n+1} \sum_{i=1}^n \ell(z_i, \lambda) + \frac{B}{n+1} \leq \alpha \right\} \end{aligned}$$

where  $B$  is assumed to be the maximum possible loss value.

$\ell(z, \lambda)$  measures how well the conformal set  $\mathcal{C}(x_i)$  covers true label  $y_i$ ,  
 $\frac{1}{n+1} \sum_{i=1}^n \ell(z_i, \lambda)$  empirical risk,  $\frac{B}{n+1}$  correction term by exchangeability.

# Bayesian Quadrature

A class of probabilistic numerical methods viewing numerical integration of  $\int_a^b f(x)dx$  as Bayesian inference in the following steps:

- 1 Place a prior  $p(f)$  on functions ,e.g., Gaussian process;
- 2 Evaluate  $f$  at  $x_1, \dots, x_n$   $y_i = f(x_i)$ ;
- 3 Compute posterior given the observed values of  $p(f \mid x_{1:n}, y_{1:n}) \propto p(f) \prod_{i=1}^n \delta(y_i - f(x_i))$ ;
- 4 Estimate

$$\int_a^b f(x)dx \approx \int_a^b f_n(x)dx, f_n(t) = \mathbb{E}[f(t) \mid x_{1:n}, y_{1:n}]$$

# Paper Motivation: Marginal $\rightarrow$ Conditional Coverage

- **Marginal coverage:**

$$\mathbb{P}\left(Y_{n+1} \in \hat{C}_n(X_{n+1}) \mid (X_i, Y_i), i \in D_1\right) \in \left[1 - \alpha, 1 - \alpha + \frac{1}{n_2+1}\right)$$

The probability or expectation  $\mathbb{P}, \mathbb{E}$  is over both calibration and test data  $i = 1, \dots, n_2 + 1 \Rightarrow$  coverage guaranteed **in aggregate** over multiple calibration sets (model trained, test data fixed), but the guarantee might not hold for each set in particular

- **Conditional coverage** on each calibration set?

$$\mathbb{P}\left(Y_{n+1} \in \hat{C}_n(x) \mid (X_i, Y_i), i \in D_1 \cup D_2, X_{n+1} = x\right) \geq 1 - \alpha$$

# Quantile as Random Variable

- By change of variable  $u = F(x)$ , the expectation of a random variable  $X$  is the integral of its quantile function over its domain

$$\mathbb{E}[X] = \int_{-\infty}^{\infty} xf(x)dx = \int_0^1 Q(u)du$$

- Consider the conditional CDF of loss functions given  $\theta$

$$F(\ell \mid \theta) \triangleq \mathbb{P}\{\ell(z_{\text{new}}, \lambda) \leq \ell \mid \theta\}$$

- The corresponding quantile function is

$$K_{\theta}(t) \equiv F_{\theta}^{-1}(t) = \inf\{\ell : F_{\theta}(\ell) \geq t\}$$

- Loss  $\ell$  as a random variable, then the expected loss is

$$\mathbb{E}[\ell(z, \lambda)] \triangleq J[K] = \int_0^1 K(t)dt$$

as a functional of the latent quantile function  $K(t)$

# Reformulate CP as BQ

- Idea: Instead of working directly on  $p(\theta \mid z_{1:n})$ , reparametrize the model using [Bayesian Quadrature for quantile function](#)
- Recall the expected loss (risk) over future data is

$$L(\theta, \lambda) = \int \ell(z_{\text{new}}, \lambda) f(z_{\text{new}} \mid \theta) dz_{\text{new}} = \mathbb{E}_{z \mid \theta} [\ell(z_{\text{new}}, \lambda)] \triangleq J[K]$$

- The posterior risk given the observed individual losses  $\ell_i = \ell(z_i, \lambda)$  is

$$\begin{aligned} r(\lambda \mid z_{1:n}) &= \mathbb{E}[L \mid z_{1:n}] = \int L(\theta, \lambda) p(\theta \mid z_{1:n}) d\theta \\ &= \mathbb{E}[L \mid \ell_{1:n}] = \int J[K] p(K \mid \ell_{1:n}) dK \end{aligned}$$

- The posterior over quantile functions is

$$\begin{aligned} p(K \mid \ell_{1:n}) &= \int p(K \mid t_{1:n}, \ell_{1:n}) p(t_{1:n} \mid \ell_{1:n}) dt_{1:n} \\ p(K \mid t_{1:n}, \ell_{1:n}) &\propto \pi(K) \prod_{i=1}^n \delta(\ell_i - K(t_i)) \end{aligned}$$

# Remove Prior Specification by an Upper Bound

- But to be assumption-free, we need to **avoid specifying prior  $p(K)$** !
- An upper bound on the posterior risk by the right rectangular rule

## Theorem 4.1

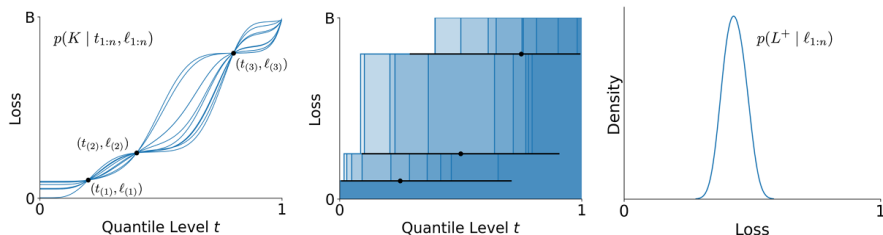
Let  $t_{(0)} = 0$ ,  $t_{(n+1)} = 1$ , and  $\ell_{(n+1)} = B$ . Then

$$\sup_{\pi} E(L \mid t_{1:n}, \ell_{1:n}) \leq \sum_{i=1}^{n+1} u_i \ell_{(i)}$$

where  $u_i = t_{(i)} - t_{(i-1)}$ .

- LHS = worst posterior risk
- RHS = piecewise-constant numerical quadrature approximation as a weighted sum of the observed losses by the spacing between consecutive quantiles

# Illustration

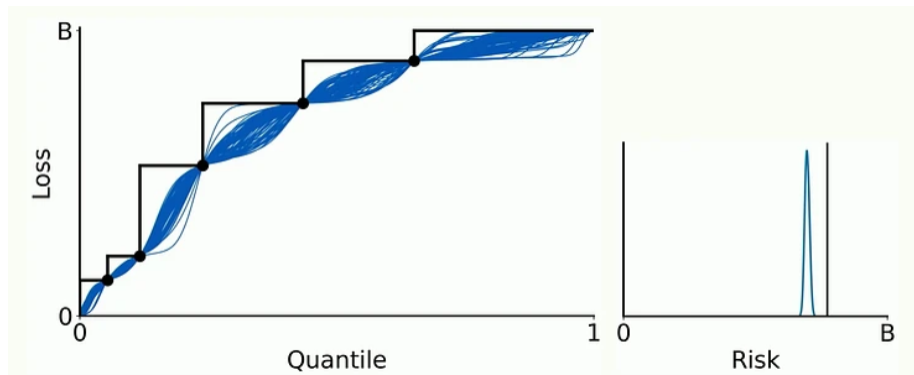


**Figure:** Left: Bayesian quadrature places a prior over the quantile function of the loss distribution. In practice, **quantile levels are not observed**.

Middle: quantile spacings with a right rectangular integration rule to construct an upper bound on the posterior distribution of the expected loss. **Randomly sampled spacings** and corresponding quantile functions are shown in blue along with a 95% credible interval for each quantile level in black.

Right: The posterior distribution for a random variable  $L^+$  that upper bounds the expected loss is constructed by integrating over the unknown quantile levels  $t_{1:n}$ .

# Illustration of Theorem 4.1



**Figure:** Regardless of priors, the stepwise function gives an upper bound on the risk (in black)



# Dirichlet Quantile Spacings & Bound Maximum Risk

- Note that we only observe the loss values  $\ell_{1:n}$ , not the quantiles  $t_{1:n}$
- It turns out the distribution of quantile spacings follows a Uniform Dirichlet  $Dir(1, \dots, 1)$ , independent of the loss distribution.

## Theorem 4.3

Define  $\ell_{(i)}$  to be the order statistics of  $\ell_1, \dots, \ell_n$  for  $i = 1, \dots, n$  and  $\ell_{(n+1)} \triangleq B$ . Let  $L^+$  be the random variable defined as follows:

$$U_1, \dots, U_{n+1} \sim \text{Dir}(1, \dots, 1), L^+ = \sum_{i=1}^{n+1} U_i \ell_{(i)}$$

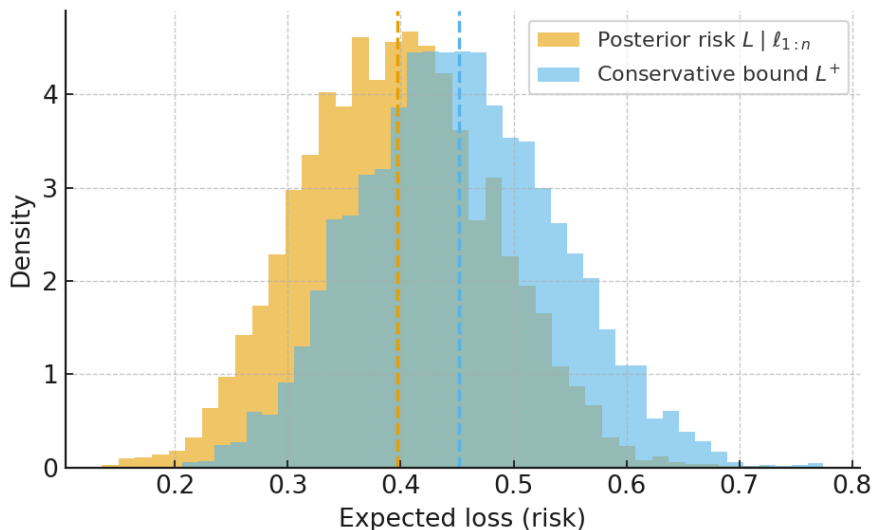
Then for any  $b \in (-\infty, B]$ ,

$$\inf_{\pi} \Pr(L \leq b \mid \ell_{1:n}) \geq \Pr(L^+ \leq b)$$

$L^+$  stochastically dominates posterior risk (density of  $L^+$  more at the right)

# Illustration of Theorem 4.3

Illustration: Posterior risk vs conservative bound  $L^+$



# Recover Conformal Methods by Posterior Mean

Then we can directly construct upper confidence bounds as follows:

## Corollary 4.4

For any desired coverage level  $1 - \alpha \in (0, 1)$ , define

$$b_{1-\alpha}^* = \inf_b \{b : \Pr(L^+ \leq b \mid \ell_{1:n}) \geq 1 - \alpha\}.$$

Then  $\inf_{\pi} \Pr(L \leq b \mid \ell_{1:n}) \geq 1 - \alpha$  for any  $b \geq b_{1-\alpha}^*$ .

The expected value of  $L^+$  recovers conformal methods:

- Split CP:

$$E(L^+) = \frac{1}{n+1} \left( n+1 - \sum_{i=1}^n \mathbb{1}\{s_i \leq s_{(k)}\} \right) = 1 - \frac{k}{n+1}$$

- Conformal Risk Control:

$$E(L^+) = \sum_{i=1}^{n+1} E(U_i) \ell_{(i)} = \frac{1}{n+1} \left( \sum_{i=1}^n \ell_i + B \right)$$